# Vishwa Sai Prathyusha

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### OBJECTIVE

Interested in exploring the application of engineering concepts and technology to solve highend challenges in the field of automation in manufacturing and special purpose robotics

EDUCATION				
Program		Institution	%/CGPA	Year of completion
<b>Dual Degree:</b> B. Tech Mechanical Engineering (M. Tech Intelligent Manufacturing)		Indian Institute of Technology Madras, Chennai	8.14/10 (9.42/10)	2016
XII (BIE)		Sri Chaitanya Junior College, Hyderabad	95.2%	2011
X (CBSE)		Kendriya Vidyalaya Sangathan, Anantapur	92%	2009
SCHOLASTIC ACHI	EVEMENTS			
<ul> <li>Visiting Graduat University of Nebr 2016)</li> <li>Vidyashree Award AISSE performance</li> </ul>	e Research Assis aska – Lincoln, USA l winner from Am e in 2009	<ul> <li>stantship at • Received Innov (Jan – May</li> <li>ul India for • Shortlisted to Exchange Pr</li> </ul>	vative Student P. e Intelligent Gr grant (Sep 2014 represent Indi ogramme (JE	roject Award from IIT round Vehicle project 4 - May 2015) a for Japan Student (NESYS) in 2008
SKILLS				
Operating Systems	Windows, Ubuntu (L	inux)		
Software and	MS Office, Arduino	, ARIA (Advanced Robotics Inter-	face for Applic	ations), ROS (Robot
Programming	Operating System), Q	t, LabVIEW, B&R Automation Stu	dio and SQL Se	rver; C++ & Python
Core	CAD (AutoCAD, ANSYS FEA and CF	PTC-Creo, ProEngineer and So D (FLUENT), CNC coding, GD&T	olidWorks), M and operation of	ATLAB, Simulink, of machine tools
PROFESSIONAL EX	PERIENCE AND I	NDUSTRIAL PROJECTS		
Position: Asst. Manager, R&D Micromatic Grinding Technologies Ltd. (Jun 2017 – 2019)	<ul> <li>Leading the Analysis, Pro</li> <li>Working on development</li> <li>Supervised is pursue tangi</li> </ul>	team and managing multiple pro- cess Development, and New Prod developing application toolkit t for medical core wires and Indus nternships and coordinated resul- ble output through a new industry	ojects in the do uct/Technology for Centerles try 4.0 solution ts to extended 7-academia coll	omains of Design and y Development ss Grinding, process is for grinders long-term projects to aboration
Project: Automation of Grinding Intelligence (AGI)	<ul> <li>Directing DH</li> <li>Produced a speed comm</li> <li>Programmed logging it interview</li> <li>Developed an</li> <li>Co-inventor of the second second</li></ul>	I-funded industry-academia collal machine with real-time multi-sen unication between machine's cont l B&R's PLC for configuring sen o a database in SQL Server n interface in LabVIEW to demons of copyrighted software for Autom	boration with A nsor interfacing roller and indu sors, processin trate in-process nation of Grindi	MTDC, IIT Madras g capability and high- strial PC ng data acquired and s data acquisition ng Intelligence
Project: Core Wire Grinding (CWG)	<ul> <li>Designing pr less than .5 n</li> <li>Coordinating</li> <li>Organized cr</li> </ul>	rocess for a medical application o nm diameter are profile-ground in g design of micro-scaled tooling an ross-functional meetings for proje	f grinding whe centerless thru d auxiliary sen ct planning an	re 2 m long shafts of ufeed grinding set-up sor requirements d indigenous product

	development ensuring continuous interaction with prospective customers
Project:	• Established direct communication with controller through a third-party software, enabling development of Computer-Aided Manufacturing (CAM) module in grinder
Mechatronics Integrated Solutions	<ul> <li>Improvised GrindTrak<sup>™</sup>, in-process diagnostic tool, to a compact and rigid version</li> <li>Developed an integral CAD/CAM software solution for non-round grinding and</li> </ul>
	profile grinding of complex surfaces such as cam shafts, kneading blocks, etc.



#### **PROJECTS AT IIT MADRAS** Modeling of duodenum using SolidWorks and simulation of digesta flow dynamics **Master's Project** using ANSYS FLUENT Designed an in vivo sensor, its sensing mechanism, and its deployment mechanism • Jun 2015 - 2016 from a micro-robotic capsule to provide dynamic feedback of mass intake (1 year) Developed an adaptive Model-based Predictive Controller using MATLAB and • Simulink as energy-intake suggestor and controller for Weight-Maintenance System Worked on the modules - Obstacle Avoidance, Path Planning and Localization • **Intelligent Ground** Adapted Vector-Field Histogram (VFH) algorithm for path planning and • Vehicle (IGV) simulated it in MobileSim with a custom generated map of the environment Integrated data obtained from LiDAR scans, odometry from encoders and IMU to • Jul 2013 - 2016 generate a map of the environment and localize the robot using **SLAM methods** in (3 years) **ROS** (Robot Operating System), tuning and customizing the sensors for three different iterations of mechanical design Design of a control law for virtual communication of mobile robots to solve the jack-• **Formation Control** knifing issue of truck-trailer accidents by replacing the mechanical link Debugged the code of formation control law in ARIA (Advanced Robotics Interface • May - Jul 2013 for Applications); simulated and tested it real-time on two Pioneer P3DX robots (8 weeks)

#### **POSITIONS OF RESPONSIBILITY (IIT MADRAS)**

Head, Sahaay (CFI) Sep 2014 - Jun 2016 (22 months)	<ul> <li>Spearheaded initiatives to improve outreach, pioneering collaboration with more NGOs to promote the idea of 'Learning with purpose' among more students</li> <li>Illustrated the need for social innovation by students with the launch of Social Entrepreneurship Club through collaboration of CFI with CSIE, IIT Madras</li> <li>Mentored successful projects like Advanced Electrolarynx, that bagged multiple awards in its working phase itself, and a Two-wheeler Ambulance</li> </ul>
Student Advisory Council Member, NSS Sep 2014 - 15 (1 year)	<ul> <li>Reviewed a set of projects undertaken in the academic year with a process of evaluation of their progress, to improve their scope and impact to serve better</li> <li>Mentored the managerial team as and when necessary in administering the NSS activities</li> <li>Advocated a project initiative in collaboration with RailTel Corporation of India</li> </ul>
Project Administration Team, NSS Jun 2013 - 14 (1 year)	<ul> <li>Selected volunteers and project representatives (PRs) based on their interests and motivation to be part of service-oriented projects</li> <li>Conducted project reviews with the Advisory Council presided by experienced faculty members and erstwhile student members of NSS</li> <li>Orchestrated four new projects, representing two of them personally, to set-up a centre for learning in the NSS Office and a congenial environment for the same</li> </ul>

## **OTHER ACTIVITIES/ACHIEVEMENTS**

- Patented (2017) and received Best Project award (2016) for Advanced Electrolarynx in CFI Annual Tech Awards
- Winner of Industry Defined Problem (IDP) posed by Titan Company for proposing an alternate method for clamping coil core during winding operation (2015)
- Was awarded "Most Enthusiastic Mentor" for the active contribution to the hostel team in Inter-hostel Tech-Soc activities of IIT Madras like manual/autonomous robotic competitions (2011 16)

#### REFERENCES

- Dr. Nitin Chandrachoodan, Associate Professor, Electrical Engineering Department, IIT Madras <u>Contact</u> [Mentored as Faculty Advisor for IGV International Competition]
- Dr. N. Arunachalam, Associate Professor, Mechanical Engineering Department, IIT Madras Contact
- Dr. P. V. Manivannan, Assistant Professor, Mechanical Engineering Department, IIT Madras Contact
- Mr. Anant Jain, Former R&D Head, Micromatic Grinding Technologies Limited, Bangalore

### **RELEVANT COURSES (GRADES: S = 92+%; A = 85% - 92%)**

- Modeling and Simulation in Manufacturing (S)
- Microprocessors in Automation (S)
- Sensors for Intelligent Manufacturing (S)
- Machine Vision and its Applications (A)
- Mechatronic Systems (A)
- Prognostics and Health Management of Machines (A)